L N	umber	Hits	Search Text	DB	Time stamp
1		63	(electric same motor same control\$5 same	USPAT;	2003/05/08 12:43
			simulat\$3).ti. or (electric same motor	US-PGPUB	2003/03/00 12:43
			same control\$5 same simulat\$3).ab.		
2		21	((electric same motor same control\$5 same	USPAT;	2003/05/08 12:22
			simulat\$3).ti. or (electric same motor	US-PGPUB	
			same control\$5 same simulat\$3).ab.) and		
	į		electric and motor and control\$5 and		1
			torque and (speed velocity rate) and		
			position	1	1 i
3		1	(((electric same motor same control\$5 same	: USPAT;	2003/05/08 12:23
			simulat\$3).ti. or (electric same motor	US-PGPUB	4
			same control\$5 same simulat\$3).ab.) and		
			electric and motor and control\$5 and		1
			torque and (speed velocity rate) and		1
			position) and numerical		T .
4		4	((electric same motor same control\$5 same	USPAT;	2003/05/08 12:41
			simulat\$3).ti. or (electric same motor	US-PGPUB	
			same control\$5 same simulat\$3).ab.) and	9 11	
_		4.4.0	numerical		
5		112	388/801	USPAT;	2003/05/08 12:41
_	İ	1.40		US-PGPUB	
6		148	(electric same motor same control\$5 same	USPAT;	2003/05/08 12:42
			simulat\$3).bsum. or (electric same motor	US-PGPUB	
			same control\$5 same simulat\$3).ab. and		
7			388/801		Tulia and
/	-	0	((electric same motor same control\$5 same	USPAT;	2003/05/08 12:44
	1	1	simulat\$3).ti. or (electric same motor	US-PGPUB	1
			same control\$5 same simulat\$3).ab.) and 388/801		
8		187			00000105100 10
Ü		107	simulat\$3).bsum. or (electric same motor	USPAT;	2003/05/08 12:44
			same control\$5 same simulat\$3).ab.	US-PGPUB	
9		0	((electric same motor same control\$5 same	HCDAM.	2002/05/00 10 44
_		١	simulat\$3).bsum. or (electric same motor	USPAT;	2003/05/08 12:44
		i	same control\$5 same simulat\$3).ab.) and	US-PGPUB	
			388/801		
10	1	749		USPAT	2003/05/08 12:53
11		3	318/799 and (((electric same motor same	USPAT	2003/05/08 12:54
	1		control\$5 same simulat\$3).ti. or (electric	OSIAI	2003/03/08 12.34
			same motor same control\$5 same		
			simulat\$3).ab.) ((electric same motor		
			<pre>same control\$5 same simulat\$3).bsum. or</pre>		
			(electric same motor same control\$5 same		_
			simulat\$3).ab.))		
12		1	(318/560 318/615 318/561) and (((electric	USPAT	2003/05/08 12:56
			same motor same control\$5 same		
			simulat\$3).ti. or (electric same motor	-	
			<pre>same control\$5 same simulat\$3).ab.)</pre>		
			((electric same motor same control\$5 same		
		ĺ	simulat\$3).bsum. or (electric same motor		
			<pre>same control\$5 same simulat\$3).ab.)) and</pre>		
			numerical		
13		1	(318/\$) and (((electric same motor same	USPAT	2003/05/08 13:01
	-		<pre>control\$5 same simulat\$3).ti. or (electric</pre>		
		-	same motor same control\$5 same	1	
	ĺ	i i	simulat\$3).ab.) ((electric same motor		
		1	same control\$5 same simulat\$3).bsum. or	! !	
			(electric same motor same control\$5 same		
1.4			simulat\$3).ab.)) and numerical		
14			(318/689 318/431 318/432) and (((electric	USPAT	2003/05/08 13:02
			same motor same control\$5 same		ļ
			simulat\$3).ti. or (electric same motor		
			same control\$5 same simulat\$3).ab.)		
	ł		((electric same motor same control\$5 same		1
	1		simulat\$3).bsum. or (electric same motor		
		J.	<pre>same control\$5 same simulat\$3).ab.)) and numerical</pre>		
			HUMELICAI	<u> </u>	

15		6 (318/689 318/431 318/432) and (((electric	USPAT	2003/05/08 13:06
		same motor same control\$5 same		
		simulat\$3).ti. or (electric same motor	1	
		same control\$5 same simulat\$3).ab.)		
		((electric same motor same control\$5 same simulat\$3).bsum. or (electric same motor		
16		same control\$5 same simulat\$3).ab.)) 5 (318/806 318/807) and (((electric same	II CDAM	2002/05/00 12 05
1		motor same control\$5 same simulat\$3).ti.	USPAT	2003/05/08 13:06
		or (electric same motor same control\$5		
	1	same simulat\$3).ab.) ((electric same		
		motor same control\$5 same simulat\$3).bsum.		
İ		or (electric same motor same control\$5		
1		same simulat\$3).ab.))		
-	1:		USPAT;	2003/05/06 16:37
			US-PGPUB	2003/03/00 10.3/
-		7 700/170 and simulat\$4 and numerical	USPAT;	2003/05/06 16:57
}			US-PGPUB	2003,03,00 10.37
-		1 700/170 and (simulat\$4 same numerical)	USPAT;	2003/05/06 17:00
			US-PGPUB	10000,00,00 11100
-		5 (simulat\$4 same numerical) and motor and	USPAT;	2003/05/06 17:53
		torque and (speed rate velocity) and	US-PGPUB	
1		position and PI and PID		
-		0 ((simulat\$4 same numerical) and motor and	USPAT;	2003/05/06 17:40
1		torque and (speed rate velocity) and	US-PGPUB	
		position and PI and PID) and transmission		
-		1 6,011,373.pn.	USPAT;	2003/05/06 17:40
			US-PGPUB	
-	2	7 (simulat\$4 same numerical) and motor and	USPAT;	2003/05/06 17:54
		torque and (speed rate velocity) and	US-PGPUB	
l _		position and (PI or PID) 2 ((simulat\$4 same numerical) and motor and		
_	4	- (mare and a second and a mocon and	USPAT;	2003/05/06 18:44
		torque and (speed rate velocity) and position and (PI or PID)) not ((simulat\$4	US-PGPUB	
		same numerical) and motor and torque and		
		(speed rate velocity) and position and PI		
		and PID)		
_	1 1	((simulat\$4 same numerical) and motor and	USPAT;	2003/05/06 18:45
		torque and (speed rate velocity) and	US-PGPUB	2003/03/06 18:45
		position and (PI or PID)) not ((simulat\$4	OS IGIOD	
		same numerical) and motor and torque and		
		(speed rate velocity) and position and PI		
		and PID) and (motor.bsum. or motor.ab.)	!	
-	6939		USPAT;	2003/05/07 12:50
		ab.	US-PGPUB	
-	814		USPAT;	2003/05/07 12:53
		or (electric same motor same	US-PGPUB	
	_	control\$5).ab.		
-	6	(electric same motor same control\$5 same	USPAT;	2003/05/07 16:21
		simulat\$3).ti. or (electric same motor	US-PGPUB	
_		same control\$5 same simulat\$3).ab.		
_		((electric same motor same control\$5 same	USPAT;	2003/05/07 13:07
		simulat\$3).ti. or (electric same motor	US-PGPUB	
		same control\$5 same simulat\$3).ab.) and electric and motor and control\$5 and		
		torque and PI and PID		
_	2		USPAT;	2003/05/07 13:18
		simulat\$3).ti. or (electric same motor	US-PGPUB	2003/05/07 13:18
		same control\$5 same simulat\$3).ab.) and	US-FGFUB	
		electric and motor and control\$5 and		
		torque		
-		(((electric same motor same control\$5 same	USPAT;	2003/05/07 13:12
		simulat\$3).ti. or (electric same motor	US-PGPUB	
		same control\$5 same simulat\$3).ab.) and	32 20200	
		electric and motor and control\$5 and		
		torque) and (speed velocity rate) and		
		podition		

-	21		USPAT;	2003/05/08 12:21
		simulat\$3).ti. or (electric same motor	US-PGPUB	
		same control\$5 same simulat\$3).ab.) and		
		electric and motor and control\$5 and		
		torque) and (speed velocity rate) and position		
1 -	11	1 -	USPAT;	2003/05/07 13:17
		same simulat\$3).ti. or (electric same	US-PGPUB	2003/03/07 13:17
		motor same control\$5 same simulat\$3).ab.)	05 10105	
		and electric and motor and control\$5 and		
		torque) and (speed velocity rate) and		
		position) and compensat\$3		
-	0	(((((electric same motor same control\$5	USPAT;	2003/05/07 13:17
		same simulat\$3).ti. or (electric same	US-PGPUB	
		motor same control\$5 same simulat\$3).ab.) and electric and motor and control\$5 and		
		torque) and (speed velocity rate) and		
		position) and compensat\$3) and numerical		
-	1		USPAT;	2003/05/07 13:18
		simulat\$3).ti. or (electric same motor	US-PGPUB	,,
		same control\$5 same simulat\$3).ab.) and		
		electric and motor and control\$5 and		ļ
_	1	torque) and numerical ((((electric same motor same control\$5	HODE	2002/05/25
	1	same simulat\$3).ti. or (electric same	USPAT;	2003/05/07 14:18
		motor same control\$5 same simulat\$3).ab.)	US-PGPUB	
		and electric and motor and control\$5 and		
		torque) and (speed velocity rate) and		
		position) and (simulat\$3 same numerical)		
-	63		USPAT;	2003/05/08 12:20
		simulat\$3).ti. or (electric same motor	US-PGPUB	
_	0	same control\$5 same simulat\$3).ab.		
	1	((electric same motor same control\$5 same simulat\$3).ti. or (electric same motor	USPAT; US-PGPUB	2003/05/07 16:28
		same control\$5 same simulat\$3).ab.) and	U3-FGFUD	
	į	(PI and PID) and numerical	: ! !	
-	0	(electric same motor same control\$5 same	USPAT;	2003/05/07 16:35
		simulat\$3) and (PI and PID) and numerical	US-PGPUB	
_	0	1 (dila	USPAT;	2003/05/07 16:36
		(PI and PID) and numerical and simulat\$3) and (simulat\$3 near numerical)	US-PGPUB	
_	0	((electric same motor same control\$5) and	USPAT;	2003/05/07 16:36
		(PI and PID) and numerical and simulat\$3)	US-PGPUB	2003/03/07 16:36
		and (simulat\$3 same numerical)	33 10102	
-	7	(electric same motor same control\$5) and	USPAT;	2003/05/07 16:37
	1	(PI and PID) and numerical and simulat\$3	US-PGPUB	1
-	115	(electric same motor same control\$5) and (PI same PID)	USPAT;	2003/05/07 16:41
_	8	((electric same motor same control\$5) and	US-PGPUB	2002/05/07 17 24
- 1	1	(PI same PID)) and numerical	USPAT; US-PGPUB	2003/05/07 17:34
- <i>a</i>	7	(((electric same motor same control\$5) and	USPAT;	2003/05/07 17:35
		(PI same PID)) and numerical) and	US-PGPUB	2505,05,07 17.55
		compensat\$3		
- 119	4	(((electric same motor same control\$5) and	USPAT;	2003/05/07 17:35
		(PI same PID)) and numerical) and	US-PGPUB	
		compensat\$3 and compensator		
_	8	(US-6356799-\$ or US-6191513-\$ or US-5726879-\$ or US-4488242-\$ or	USPAT	2003/05/07 18:25
		US-6505085-\$ or US-5428285-\$ or		
		US-5206575-\$ or US-6198246-\$).did.		
_	4	((US-6356799-\$ or US-6191513-\$ or	USPAT;	2003/05/07 18:26
		US-5726879-\$ or US-4488242-\$ or	US-PGPUB	,,
		US-6505085-\$ or US-5428285-\$ or		
		US-5206575-\$ or US-6198246-\$).did.) and		
_	8	(parameter same simulat\$3)		0000/0-1
		(US-6198246-\$ or US-5206575-\$ or US-6505085-\$ or US-6356799-\$ or	USPAT	2003/05/08 10:28
		US-6191513-\$ or US-5726879-\$ or		
	<u> </u>	US-5428285-\$ or US-4488242-\$).did.	İ	

- 2	((US-6198246-\$ or US-5206575-\$ or US-6505085-\$ or US-6356799-\$ or US-6191513-\$ or US-5726879-\$ or US-5428285-\$ or US-4488242-\$).did.) and	USPAT; US-PGPUB	2003/05/08 10:29
	simulat\$3.bsum.		